

SIEMENS



SINAMICS G120

Multimedia Training Package

www.siemens.com/sinamics-g120

Required System Configuration CD-ROM

- Processor with min. 2 GHz (dual core recommended)
- 1024 MB RAM
- Graphics card (min. 256 MB memory recommended)
- Screen resolution: 1280 x 1024 px
- Operating Systems:
 - Microsoft® Windows™ XP (Service Pack 2 or later)
 - Microsoft® Windows™ Vista
 - Microsoft® Windows™ 7

SINAMICS G120

Training Booklet



This booklet contains the same information as the attached CD. Still, we highly recommend to work through the learning program before consulting the booklet. The multimedia tutorial is a comfortable and easy to understand introduction to the converter family SINAMICS G120.

04/2012

6FC5095-0AA85-0BA0

Safety instructions

Validity

These instructions apply to the following converter:

Product

SINAMICS G120

Prerequisites

You are proficient in working with the Microsoft® Windows™ operating system.
You are conversant with the principles of electronics and electrical engineering.

Warning

Dangerous currents and voltages!

The equipment contains dangerous voltages and controls potentially dangerous rotating mechanical parts. Non-compliance with the warnings or failure to follow the instructions contained in the documentation can result in loss of life, severe personal injury or serious damage to property.

Take particular notice of the general and regional installation and safety regulations regarding work on dangerous voltage installations (e.g. EN 50178) as well as the relevant regulations regarding the correct use of tools and personal protective equipment (PPE).



Qualified Personnel

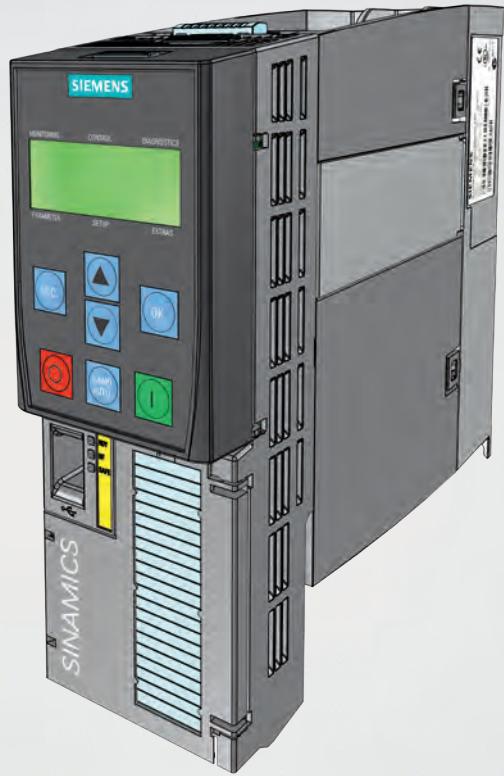
The device/system may only be set up and used in conjunction with this documentation. Commissioning and operation of a device/system may only be performed by qualified personnel. Within the context of the safety notes in this documentation, qualified persons are defined as persons who are authorized to commission, ground and label devices, systems and circuits in accordance with established safety practices and standards.

Disclaimer of Liability

Depending upon the firmware and software version of the Control Unit, of the Operator Panel and of the STARTER, the masks, symbols and menus may differ. We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

Welcome to the SINAMICS G120 Tutorial for First Time Users. This tutorial will help acquaint you simply, quickly and comfortably with the frequency converter. We'll take you step by step through installation, setting parameters and initial start-up. We recommend that you don't skip any chapters.

Converter family SINAMICS G120		08–21
1.1 Components	Power Module Control Unit Operator Panel 2 (BOP-2/IOP)	12 13 14
1.2 Mounting and wiring	Power Module Control Unit Operator Panels (BOP-2/IOP)	15 18 20
Operator Panels BOP-2 and IOP		22–41
2.1 Basic functions	The BOP-2 display Menu structure	24 25
2.2 Working with BOP-2	Parameter list Operating pattern Function buttons	27 27 29
2.3 Quick commissioning	Resetting the converter Setting the control mode Selecting line frequency Entering motor data Specifying application parameters Saving and restoring data	30 31 31 32 33 35
2.4 Intelligent Operator Panel	The device Working with IOP	37 38
STARTER software and PC		42–73
3.1 Mounting and preparation	Creating a STARTER project STARTER user interface Loading converter data	46 49 50
3.2 Parameterization	Configuration wizard Safety Integrated Start motor data identification	54 58 62
3.3 Application cases	Setting setpoint specifications Saving data Restoring factory settings	65 67 70
Appendix	Download overview	75



Converter family

SINAMICS G120

1.1 Components

The SINAMICS G120 frequency converter is modular.
It comprises of three basic components:



1

The Power Module supplies
voltage to the motor

2

The Control Unit controls and
monitors the Power Module

3

The Basic Operator Panel (BOP-2) and the Intelligent Operator Panel (IOP) are used to operate and monitor the converter



+

The optional PC Connection Kit-2 can also be used to set parameters, operate and monitor the converter; the kit is required in order to establish communication between a PC and the Control Unit



Each Control Unit can be freely combined with each Power Module.

NOTE

Power Module

The device is available in several sizes. Its power range is between 0.37 kW and 250 kW. The picture shows the PM240-2 frame size A.



Control Unit

There are various designs for the Control Units. They differ primarily in terms of the control terminal assignments as well as in terms of different field bus interfaces. This tutorial will use the example of the CU240E-2 Control Unit. It was developed for stand-alone operation.



An overview of the various control unit versions and their differentiation can be found in the official SINAMICS G120 brochure at:
<http://www.siemens.com/sinamics-g120/printmaterial>

NOTE

Basic Operator Panel 2 (BOP-2)

The basic input and display device is used to operate and set parameters for the converter after being connected to the Control Unit. It is operated by pressing the buttons and features a simple commissioning thanks to the menu prompting and the 2-line display.

Intelligent Operator Panel

The Intelligent Operator Panel manages the same functions as the BOP-2 but adds several more options. The integrated application wizard, full graphical diagnostic overviews and plain text increase usability substantially. It is available in various versions and can be used drive-externally for series commissioning and on-site diagnosis.



BOP-2

- 1 Seven operating buttons
- 2 Display
- 3 Release catch
- 4 Door mounting screw recess
- 5 RS232 connector
- 6 Product rating label



IOP

- 1 Graphical display
- 2 Navigation wheel
- 3 Five operating buttons
- 4 USB connection
- 5 RS232 connector
- 6 Product rating label

1.2 Mounting and wiring

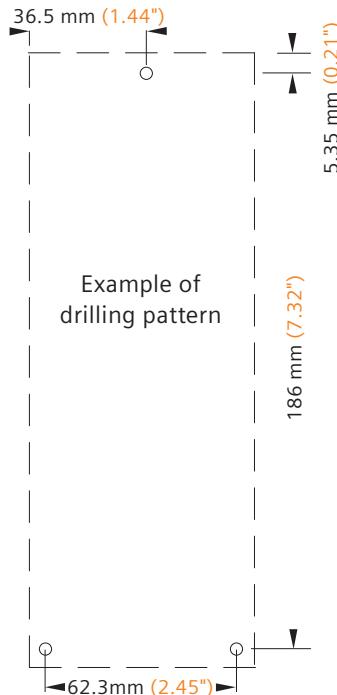
Before starting assembly, check to ensure the following conditions have been met:

- All required components, tools and small parts have been prepared
- All required cables and lines have been laid in accordance with specifications
- All minimum clearances are being observed

The 5 Safety Regulations must be strictly observed

- Disconnect
- Secure against unintentional restart
- Verify that it is free of voltage
- Ground and bypass
- Cover and shield any adjacent live parts

Mounting of the Power Module into the switch cabinet



Please refer to the drilling pattern accompanying the Power Module for the correct drilling centers and clearance distances above and below the Power Module.



Normally the motor and converter are selected in such a way that they match each other. This is also the case in our example. However, the data from the rating plate of the motor are important for the initial start-up of the converter.

NOTE

Connecting the Power Module to the motor

Depending on the operating environment, different cable length limits are required for the connection between the Power Module and motor. Unshielded cables up to 100 m in length are possible in industrial electrical networks.

Wiring the Power Module

- 1 • Connect the phases and the earth conductor to the terminals U2, V2, W2 and PE

Wiring the motor

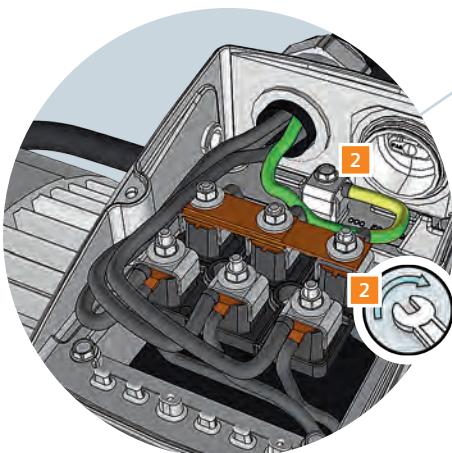
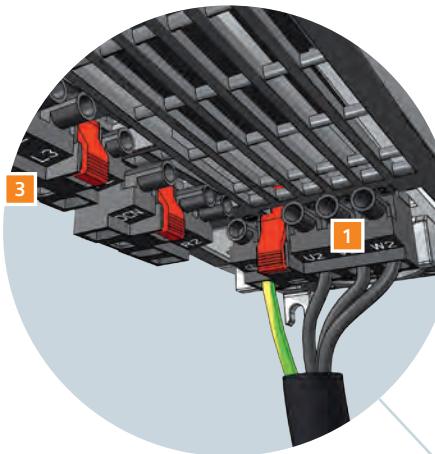
- 2 • Unscrew the cover to the terminal box on the motor (the inside cover of Siemens' motors illustrates the possible wiring for the Star connection and the Delta connection)
 - Remove the bridge rails from the connecting block and loosen the screws
 - Place the bridge rails on the terminal block and screw them into place (depending on the type of connections required – Star or Delta, in this example a Star connection is shown)
 - Insert the cables from the Power Module through the opening of the terminal box to the motor
 - Connect the PE connection first
 - Slide the phases in accordance to the phase assignment in the connections
 - Replace the terminal cover and ensure it is secured with the four screws to the required torque

The motor and Power Module are now connected.

Wiring the power supply

- 3 • Connect the phases and the earth conductor to the pluggable terminal clamps L1, L2, L3 and PE

The electrical wiring is now complete.



Motor lines represent interfering transmitters. As a result, you should use shielded cable in order to meet the corresponding electromagnetic compatibility conditions. The cable lengths that are actually possible depend upon the following:

- Operating environment
- Converter being used
- Reactors and filters used
- Shielded or unshielded cable

In order to meet Class A electromagnetic compatibility requirements, you need a filter and a shielded cable (max. length: 25 meters).

The depicted example shows a Star connection. The rating plate provides information about the correct circuit data: e.g. 230/400 V Δ/Y means that you are connecting the motor in Y with a 400 V network.

NOTE

Attaching the Control Unit

Connect the Control Unit with the fastening clips on the bottom of the Power Module and then press the upper edge of the Control Unit against the Power Module until the locking device snaps into place. Before wiring the control terminals, the terminal cover has to be opened.

General procedure for wiring with the cage clamp mechanism

- Slide the wire into the terminal opening
- The inner clamp opens slightly and snaps the wire tightly into place

The wire is now firmly attached.

- To release the wire press a screw driver onto the lever
- Remove the wire
- Withdraw the screwdriver from the terminal

Wiring the control terminals in the CU240E-2

1 The potentiometer:

- Attach the positive pole of the supply voltage to 1
- Attach the negative pole to 2
- Wire the output of the potentiometer arm to 3
- Close the circuit by connecting 4 with negative pole 2

2 On/Off, Reverse, and Reset buttons:

- Wire the button's power supply to 9
- Attach the associated digital inputs to terminals 5, 6 and 7
- To close the circuit, connect 28 and 69 to 34

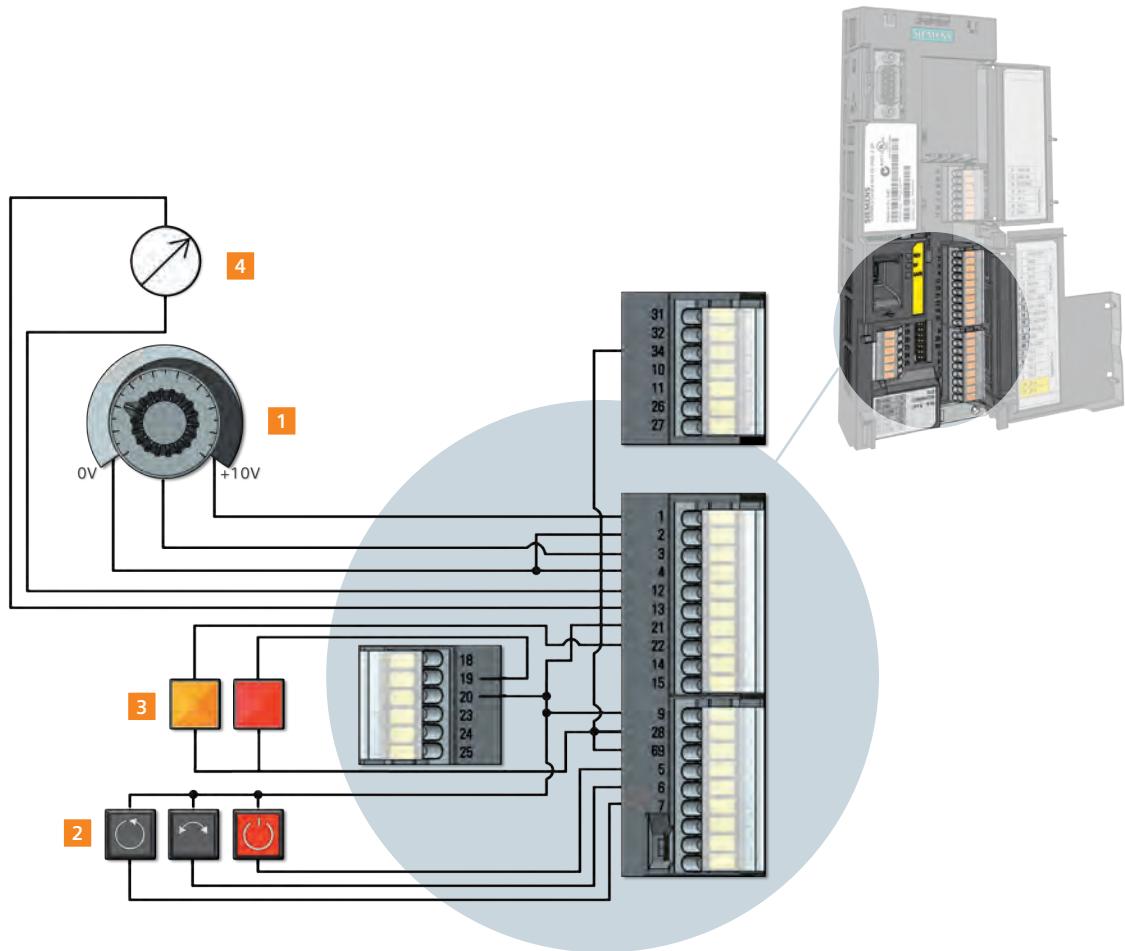
3 Indicator lamps:

- Connect 9 with 20 and 21 to attach the power supply for the LEDs
- Wire the Faults LED to digital output 19 and the Warning LED to digital output 22
- Connect the negative pole to terminal 28

4 Display for frequency output:

- Connect the positive pole to 12
- Connect the negative pole to 13

The wiring is now complete.



Mounting the Operator Panels (BOP-2 or IOP)

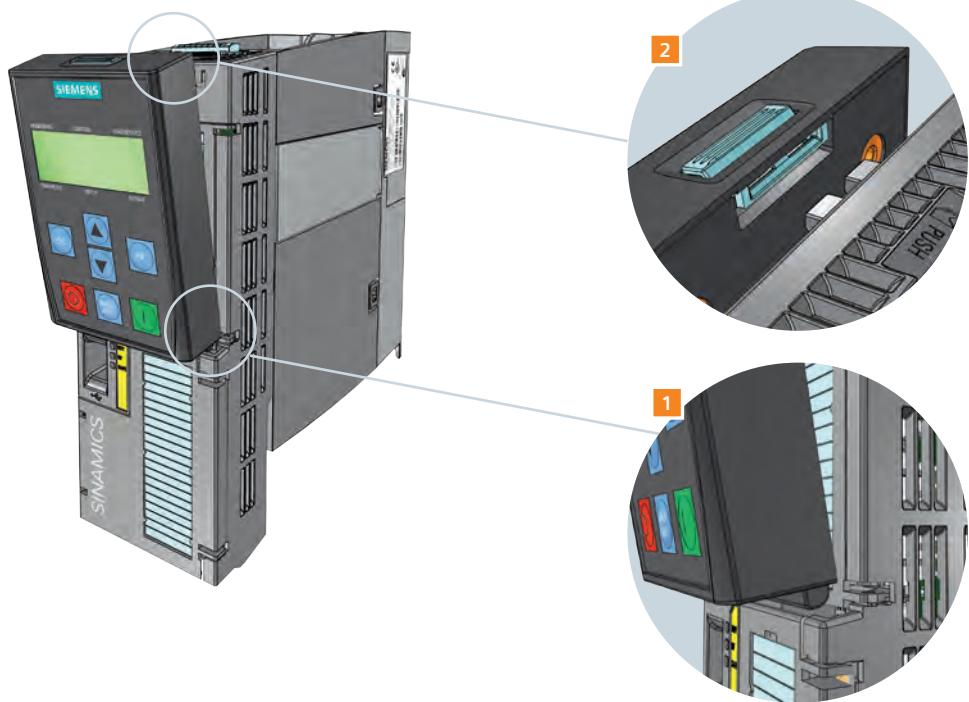
- Remove the cover of the RS232 connection by lifting it up and sliding it to the side

1

- Place the bottom edge of the IOP/BOP-2 into the lower recess of the Control Unit housing

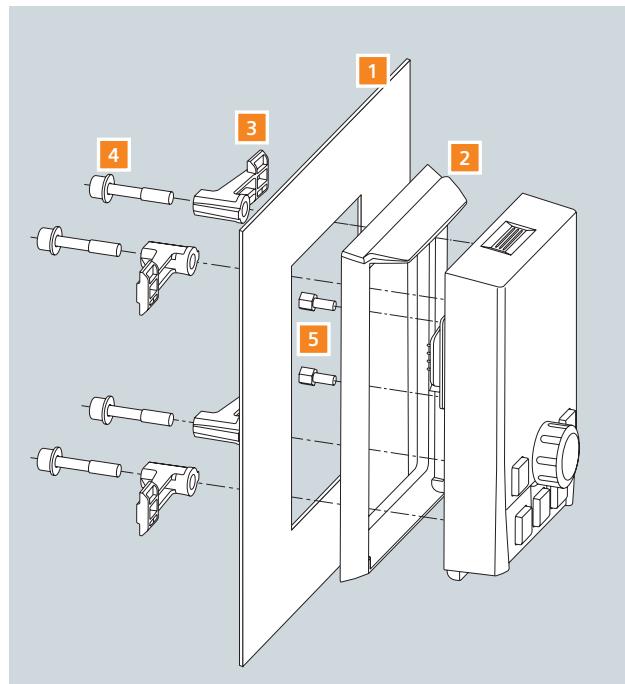
2

- Push the IOP/BOP-2 toward the Control Unit until the release-catch clicks into place



Mounting the IOP or BOP-2 in a cabinet door

The operator panels can simply be mounted in a control cabinet door with just a few manual operations using the optionally available door mounting kit. Degree of protection IP55 / UL type 12 is achieved when mounting them in the control cabinet door.



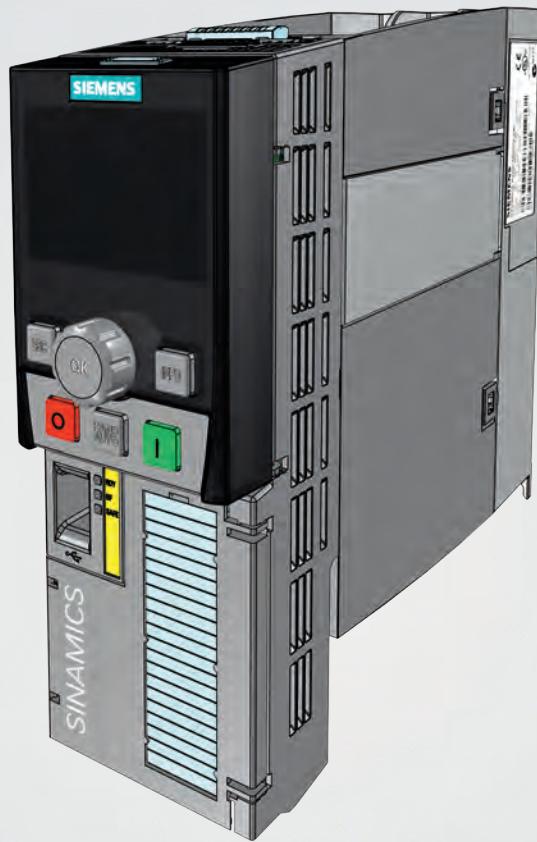
- 1** Door panel
- 2** Seal
- 3** Door mounting bracket
- 4** Screws
- 5** D-type retaining screws

Mounting the IOP
Identical mounting with BOP-2

Congratulations! Your converter is now ready for operation.
After assembly is completed, the converter's parameters must be set up, i.e., you must give the converter the specific characteristics of the attached motor.

In this section, you will learn more about the usage of Operator Panels to control the converter locally on-site. You'll learn how to use the Basic Operator Panel 2 (BOP-2) to set up parameters for the converter and the attached motor and how to operate the converter with the BOP-2. Then, you will learn how to use the Intelligent Operator Panel (IOP) to your advantage.

2



Basic Operator Panel (BOP-2) Intelligent Operator Panel (IOP)

2.1 Basic functions

The Operator Panel is the input and display instrument for controlling the converter. It is used in stand-alone operation, i.e., locally, on the device, integrated in the cabinet door or as handheld version for series setup (IOP).

The BOP-2 display

The BOP-2 is used to commission, diagnose (troubleshoot) and display the status of the converter. Up to 2 status values can be simultaneously and continuously monitored. It features a simple navigation using a transparent and well-structured menu and clearly assigned operator keys.



- 1 Menu bar indicates the selected menu function (see page 25)
- 2 Provides information about the selected functionality or displays the actual value
- 3 Displays the values



In this tutorial, we introduce an application that is based on "V/f control with linear characteristic curve". This control method is typically applied for conveyor belt applications. We recommend that you work through the example we have presented here in order to familiarize yourself with setting up parameters for a converter.

NOTE

Menu structure

When moving the menu bar to the following menu function, the following applies:

1 MONITORING

The actual status of the converter/motor system is displayed

2 CONTROL

Setpoint, Jog and Reverse mode can be activated

3 DIAGNOSTICS

Faults and alarms can be acknowledged, history and status is displayed

4 PARAMETER

Parameter values can be viewed and changed

5 SETUP

Basic commissioning of the converter can be performed

6 EXTRAS

Additional functions such as saving and copying data sets into and from the BOP-2 can be performed



2.2 Working with BOP-2

The BOP-2 has got seven buttons. For setup and parameterization only the UP and DOWN, OK and ESC buttons are relevant. The ON, OFF and HAND/AUTO keys are needed for local operation.



- 1 ESC key – Takes you back to the previous screen
- 2 Up key – Change selection
- 3 Down key – Change selection
- 4 OK key – Confirm the selection
- 5 OFF key – Stops the motor in manual mode
- 6 HAND/AUTO key – Switches the command source between HAND and AUTO mode
- 7 ON/RUN key – Starts the Motor in manual mode

Parameter list

To better understand the functionality of the buttons, you should be acquainted with the operating pattern: The Basic Operator Panel gives you access to a parameter list. Stored behind the parameters are parameter values that control the operation of the motor. However, not all the numbers are assigned.

Operating pattern

- Press ESC to enter the menu selection
- Use the UP and DOWN buttons to move the menu bar to PARAMS and press OK
- Press OK to select the Standard Level

Example

ESC ➤ ▲ ▼ ➤ PARAMS ➤ OK

The first parameter number that appears is displayed on the left side of the screen: r2 (r stands for read only and means that you can only read this value but cannot change it). On the right side, the parameter value of the selected number is shown.

- Press UP to access the next parameter
- In this case, P3 appears (P means that you can change the value of this parameter)
- Press OK to edit the parameter
- Use the UP and DOWN buttons to adjust the value
- Confirm the value by pressing OK

Example

ESC ➤ ▲ ▼ ➤ PARAMS ➤ OK ➤ ▲ ▼
STANDARD ➤ OK ➤ ▲ ▼ ➤ P3 ➤ OK



If you want to change any parameter using the parameter list, you are requested to choose a filter level (Standard or Expert). The Standard Level limits the available parameters, thus limiting the risk of dangerous parameters. The Expert Level gives access to all parameters.

NOTE

Some parameters store more than one value. In this case, pressing OK does not take you directly to the value, but to an index that is displayed in brackets [00] above the actual value.

Example for index parameters

- Pressing OK takes you to [00]
- UP takes you to [01], DOWN back to [00]
- Decide for an index number of your choice
- Press OK again to edit the index
- The value starts flashing
- Adjust the value by pressing UP and DOWN
- Confirm by pressing OK

Example

P 1000 → OK 00 → ▲ 0 | → OK → ▲ 3 → OK



A complete list of all parameters can be found in the "Parameter Manual: Control Units – CU240E/B-2" as a download at: <http://support.automation.siemens.com/WW/view/en/49946755>

If you want to adjust any blinking/active value digit by digit (using the UP and DOWN button might just take too long), you can always press the OK button longer than two seconds. After releasing the button, you can change any single digit by using the buttons OK (move to next digit), ESC (move to previous digit), UP (increase value), and DOWN (decrease value).

NOTE

Function buttons

With the function buttons, you can actually operate the motor. The HAND/AUTO button changes the command source between the BOP-2 (HAND) and field bus (AUTO). A hand icon appears in the screen to indicate HAND mode is active.

- In HAND mode the ON and OFF buttons are enabled
- In AUTO mode the ON and OFF buttons are disabled
- If HAND mode is active, pressing the HAND/AUTO button will switch the converter to AUTO mode
- If AUTO mode is active, pressing the HAND/AUTO button will switch the converter to HAND mode
- Changing HAND to AUTO mode is possible while the motor is still running

Screen Icons

The BOP-2 displays a number of icons at the left-hand side of the display to indicate the actual state of the converter.

- Command source auto/hand 
- Converter status running 
- JOG 
- Fault / Alarms active 



A detailed list of the Fault and Alarm messages can be found in the "Parameter Manual: Control Units – CU240E/B-2" as a download at: <http://support.automation.siemens.com/WW/view/en/49946755>

NOTE

2.3 Quick commissioning

The following descriptions show how to set up the drive using the quick commissioning wizard integrated in the BOP-2.

Starting quick commissioning

- Press ESC to enter the menu selection
- Use UP and DOWN to move the menu bar to SETUP and press OK
- The screen will automatically display the next parameter in the commissioning sequence

ESC → ▲ ▼ → **SETUP** → OK

Quick commissioning begins now. It will help you set all relevant parameters step by step. Parameters that are not relevant will be skipped automatically. Thus, you adjust the factory settings of your converter to the requirements of your motor.

Resetting the converter

- Press OK while the BOP-2 shows RESET
- Press UP or DOWN to change the value to YES
- Press OK and wait until the BUSY sign disappears
- Now all values are reset to the factory setting

RESET → OK → ▲ ▼ → YES → OK → BUSY



Any step of the commissioning wizard can be skipped by pressing the DOWN button. Going back one step can be done by pressing the UP button. By confirming one step with OK, the screen will automatically display the next parameter in the commissioning sequence.

NOTE

Setting the control mode (P1300)

In our example it is assumed that your converter and the motor are new. As a result, a series of preparatory steps are required, e.g. selecting the control mode. This is indicated by the parameter number 1300. 'V/f control with linear characteristic curve' is defined by the factory setting.

- Press OK to modify the parameter value CTRL MOD
- The upper row shows the control mode associated to the actual parameter value below
- Choose your desired control mode value by pressing UP or DOWN
- See how the control mode name in the upper row changes accordingly
- Press OK if the desired control mode is displayed

CTRL MOD > OK > ▲ ▼ > VF LIN > OK

Selecting line frequency (P100)

The next parameter sequence sets the line frequency of the region in which the motor is being used. In our example, this is Europe.

- Press OK to modify the parameter value EUR USA
- Set 0 for Europe (50 Hz) (1 represents the US line frequency of 60 Hz)
- Confirm the value by pressing OK
- The screen will automatically display the next parameter in the commissioning sequence

EUR USA > OK > 0 > OK



The applicable line frequency can be also found on your motor plate (see chapter "Entering motor data").

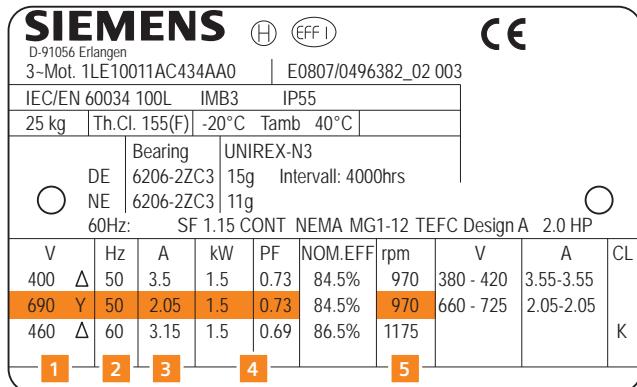
NOTE

Entering motor data

In the next step, the converter is adjusted to the motor. The motor data can be found on the motor's rating plate. Please set the values according to the plate.

- Press OK to edit the motor voltage stored under P304
- The preset motor voltage of 400 volts is displayed
- Leave the value and confirm by pressing OK

OK 00 → OK → 400 → OK



- 1 P304 = MOT VOLT = Motor voltage
- 2 P100 = EUR USA = Standard IEC or NEMA
- 3 P305 = MOT CURR = Motor rated current
- 4 P307 = MOT POW = Motor rated power
- 5 P311 = MOT RPM = Motor rated speed

The line frequency has been set already in the beginning of quick commissioning (see page 31.).



If you want to adjust any flashing value digit by digit (using the UP and DOWN button might just take too long) press the OK button longer than two seconds. After releasing the button, you can change each single digit by using the buttons OK (move to next digit), ESC (move to previous digit), UP (increase value) and DOWN (decrease value).

NOTE

Motor data identification

After entering the motor data, the wizard asks to activate the motor data identification. This is recommended for a live verification and optimization of the data that you have entered. The motor data identification initiates a “measurement” of the connected motor. In the process, the data previously calculated in the converter are compared to the actual motor data and adapted to one another.

Activating motor data identification (P1900)

- Press OK to confirm MOT ID
- Change the displayed value to 1 by pressing UP



Motor data identification does only start after the basic commissioning sequence has been completed and the motor is switched on the first time!

Specifying application parameters

In the next step, pre-defined settings for the converter's interfaces can be activated. This is stored in parameter number 15 and indicated by MAC PAr for macro parameterization. For example, the converter offers different pre-defined macros for setting the command and setpoint source.

Activating pre-defined settings (P15) e.g. for command and setpoint source

- Press OK to activate macro parameterization MAC PAr
- Macro 12 (Std ASP) is displayed, it determines DI 0 for the command source and the potentiometer for the setpoint source
- Leave the value and confirm by pressing OK



The converter can now be turned on using digital input DI 0.
The setpoint source is specified as the potentiometer.

Minimum frequency, ramp up and ramp down time (P1080)

- Set the minimum frequency under parameter MIN RPM
- Press OK (Parameter MIN RPM)
- Change the value by pressing UP or DOWN
- Press OK to confirm

MIN RPM → OK → ▲ ▼ → OK

- Set the ramping-up time under parameter RAMP UP for acceleration time to maximum frequency (P1120)
- Set the ramping-down time under parameter RAMP DWN for time until standstill (P1121)

RAMP UP → OK → ▲ ▼ → OK

RAMP DWN → OK → ▲ ▼ → OK

The values are displayed in seconds. In both cases, the times indicated should not be too short, because this might result in an alarm.



Completing quick commissioning

- Press OK while the BOP-2 shows FINISH
- Select YES and press OK again

FINISH → OK → ▲ → YES → OK

The converter is now parameterized optimally to your application and motor specifications. Now motor data identification should be performed to finalize the commissioning. This can be done by switching on the motor. At the moment, command source is set to digital input DI 0. Start the motor with turning on DI 0.

Changing the value digit by digit is possible by pressing the OK button longer than 2 seconds. After releasing the button, each single digit can be changed by using the buttons OK (move to next digit), ESC (move to previous digit), UP (increase value) and DOWN (decrease value).

Refer to the "Parameter Manual: Control Units – CU240E/B-2" for a description of the control modes and their corresponding parameter settings at: <http://support.automation.siemens.com/WW/view/en/49946755>

NOTE

Motor data identification

- Start the motor manually by using digital input DI 0
- The measuring process is set in motion
- When finished, the motor switches off
- BOP-2 indicates that the measured values are now being converted into data

Saving and restoring data

Saving data in different location is important. The EXTRAS function allows loading parameter data from the converter memory to the BOP-2 and vice versa.

Saving parameter sets from converter to BOP-2

- Navigate with the menu bar to the function EXTRAS
- Press OK
- Push the DOWN button until TO BOP appears
- Press OK

EXTRAS → OK → ▼ → TO BOP → OK

Copying parameter sets from BOP-2 to converter

- Navigate to the menu EXTRAS
- Press OK
- Push the DOWN button until FROM BOP appears
- Press OK

EXTRAS → OK → ▼ → FROM BOP → OK

The Basic Operator Panel 2 can also be used to make a variety of other adjustments to your application. Please note that an overview of the parameter numbers can be found in the Operating Instructions: Control Units CU240E-2.



The BOP-2 can be mounted or removed at any time. The device is not necessary for ongoing operation.

NOTE

2.4 Intelligent Operator Panel

With the Intelligent Operator Panel, you can set the inverter parameters, put the inverter into operation, monitor the ongoing operation of the motor, and get valuable information about faults and alarms. All these functions can be accessed without expert knowledge. The main advantages are as follows:

Fast commissioning without expert knowledge

- Simple commissioning of standard applications using application-specific assistants, no knowledge of parameter structure necessary
- User customized parameter lists with reduced parameter sets
- Simple local commissioning using the handheld version
- Fast multiple commissioning with clone function
- Commissioning without documentation by using the integrated help function

Minimization of maintenance time

- Diagnosis with clear text display, without documentation usable on site
- Simple update of languages, application assistants and firmware using the integrated USB connection
- Integrated clear text help function to read and resolve fault messages and reasons locally

High usability, intuitive handling

- Direct, manual control of the drive – simple switching from local to remote operation
- Intuitive menu navigation using wheel-click interface
- Graphical display for i.e. status values in vertical-bar charts (for example pressure or flow rate)
- Status display with freely selectable units – display of real, physical values

Flexible usage

- Available for direct control unit mounting, for door mounting or as handheld version (depending on frequency converter type)
- Simple and fast mechanical and electrical door mounting
- Handheld usable for a large variety of frequency converters
- 5 integrated languages

The device

The IOP is a menu-driven device. Its functionality is structured by three options:



- 1 [Wizards] Assists you to set up standard applications
- 2 [Control] Allows you to change setpoint value, turning direction activates the jog function in real-time
- 3 [Menu] Gives you access to all possible functionalities

The display

All necessary information is user-friendly displayed in plain text or icons. The displayed icons are shown at the top right-hand edge of the display. They indicate various states of the converter.

- Command source auto / hand
- Inverter status ready / running
- Fault
- Alarm pending
- Battery condition Fully Charged / Discharged



Working with IOP

The IOP is operated mainly by using the push-wheel. The five additional buttons make it possible to display certain values or to switch between manual and auto mode. The buttons are called: ON key, OFF key, ESC key, INFO key and HAND/AUTO key.



- 1 Turning changes the selection
Pressing confirms the selection
- 2 Starts the motor in manual mode
- 3 Stops the motor in manual mode
- 4 Takes you back to the previous screen
- 5 Displays additional information
- 6 Switches the command source between HAND and AUTO mode



The HAND/AUTO function works identically to the one implemented in the BOP-2. After starting the motor with the ON button, you can change the setpoint speed by navigating to CONTROL/SETPOINT and turning the wheel (right to increase speed, left to decrease speed).

NOTE

The wizards

There are several wizards which allow you to set up various functions and commission the converter. They navigate you interactively through the parameterization of standard applications. The wizards are accessed from the wizard menu, at the bottom-left of the status screen.

Example: Basic commissioning

- Use the wheel to highlight the word WIZARDS
- Confirm by pressing OK
- Navigate to BASIC COMMISSIONING by turning the wheel
- Confirm by pressing OK



Now the wizard will guide you step by step through the basic commissioning process by presenting a number of screens where you can choose the necessary options and values. At the conclusion of the basic commissioning process, the data can be saved to the converters memory, and calculation of motor and control data is started.

- Always use the wheel to select an option and press OK to confirm
- Press ESC to move back one step
- Press INFO to read context-sensitive help information



On the top of the screen, you can see numbers that indicate the present step of the wizard that you are in. 2/15 for example means that you are in step 2 of 15.

NOTE

Accessing diagnostics

If you want to find out which input and output devices are connected to the converter, simply navigate to the diagnostics menu and select the I/O STATUS. This option displays a list of the digital and analog inputs and outputs of the converter. In addition, you can monitor their current status. This is an information screen and cannot be changed.

Reading the I/O status

- Use the wheel to highlight the word MENU
- Confirm by pressing OK
- Select DIAGNOSTICS
- Confirm by pressing OK
- Choose I/O STATUS
- Confirm by pressing OK
- Choose STATUS DIGITAL INPUTS
- Confirm by pressing OK



You can now see a clearly arranged overview of all connected I/O including their status.

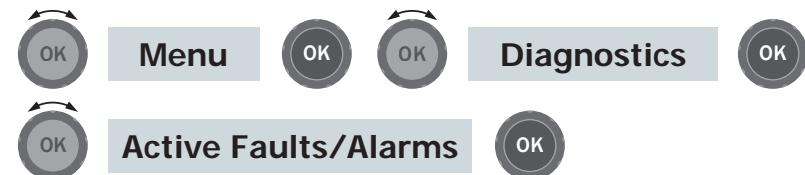


Using the button INFO, always gives you more in-depth information on the presently highlighted parameter, step or feature.

NOTE

Getting information on active faults

- Use the wheel to highlight the word MENU
- Confirm by pressing OK
- Choose DIAGNOSTICS
- Confirm by pressing OK
- Select ACTIVE FAULTS/ALARMS



Now, all active fault messages that have not yet been acknowledged are displayed. To get further information, you can highlight each one and press INFO.

You now know how to use the Operator Panels to set the parameters on your converter and start it up. A further possibility is setting up the parameters using your PC or a SIMATIC programming device. This method is clearer and more convenient, but requires somewhat more preparation time.

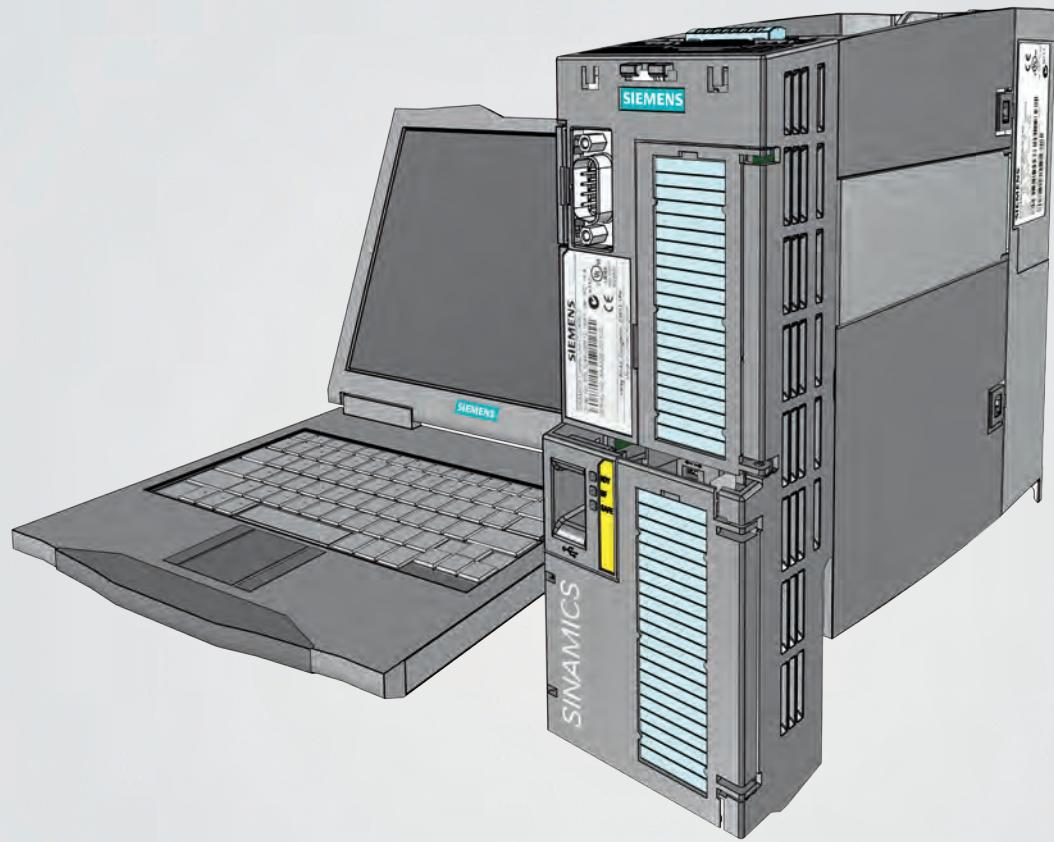


If you want to find out about previous faults and alarms, please navigate back one level and select "History". This will display a list of all previous faults and alarms including the time they occurred.

NOTE

In the next step, you will learn how to connect your PC or PG to the converter and how to set parameters with the STARTER software. With STARTER, you can also easily activate the Safety Integrated functions of the drive.

3



STARTER software and PC

3.1 Mounting and preparation

The optional PC Connection Kit 2 is required to set up the parameters using a PC.
The kit consists of two components.



1

Connecting cable



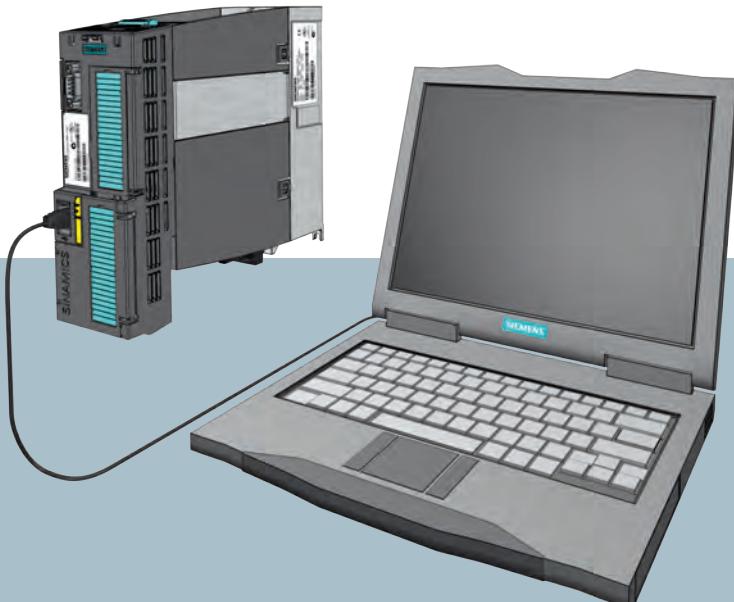
2

STARTER software on DVD

Hardware preparation

- Place the STARTER DVD into your DVD drive
- Install the STARTER software by following the setup wizard
- Connect the USB cable to the Control Unit
- Connect the other end to the USB interface of your PC

You must install the USB driver if you are connecting the converter and PC together for the first time. Windows 7 automatically installs the driver; for older Windows versions, you must confirm the automatic installation.



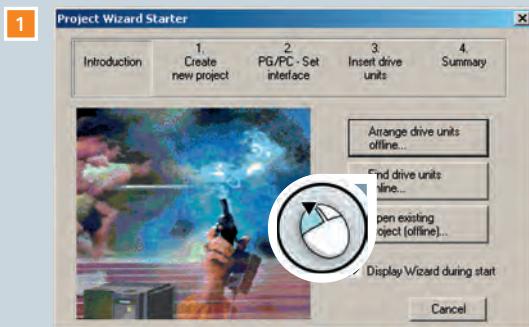
The STARTER is also available as a download at: <http://support.automation.siemens.com/WW/view/en/26233208>

NOTE

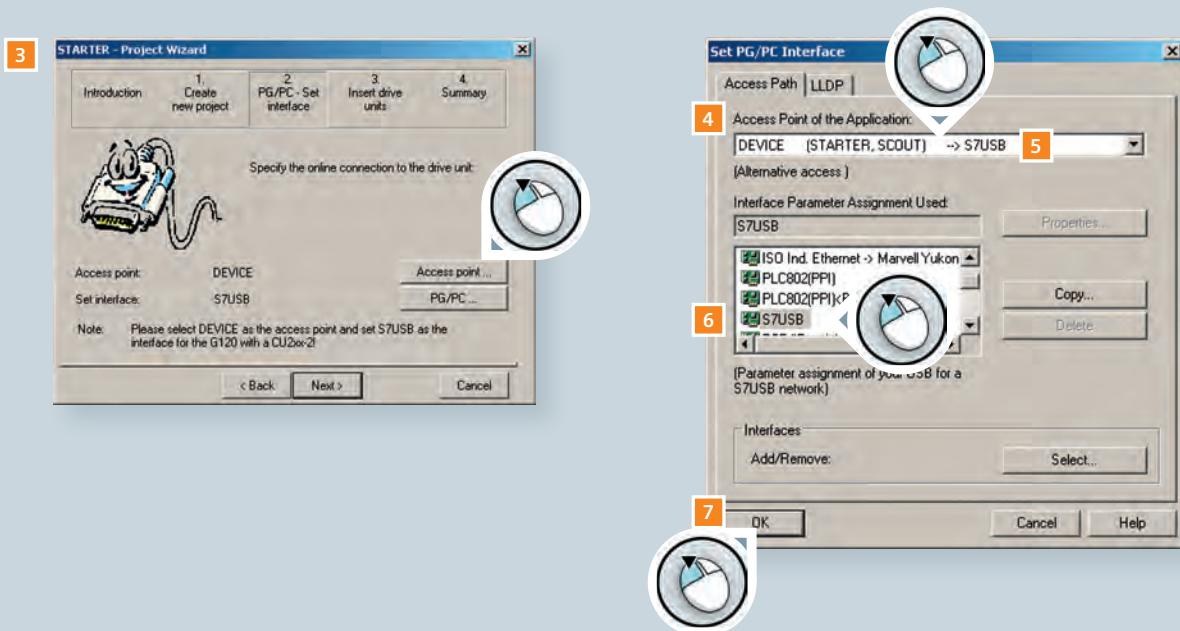
Creating a STARTER project

After installation is complete, switch on the converter's power supply and start the program. The project wizard opens automatically. The wizard will help you create your first project.

- 1 Select "Find drive units online"
- 2 Give the project a name and click "Continue"

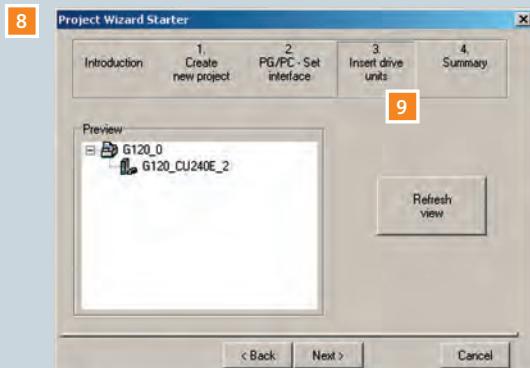


- 3 Check that "DEVICE" is set as Access point. If not, choose "Access point..." and set "DEVICE" in the dialog box "Set Access Point for Accessible Nodes". Check that "S7USB" is set as interface. If not, choose "PG/PC ...".
- 4 Open the drop-down menu "Access Point of the Application"
- 5 Choose the command "DEVICE (STARTER – SCOUT) --> S7USB"
- 6 In "Interface Parameter Assignment Used" select "S7USB"
- 7 Close with OK



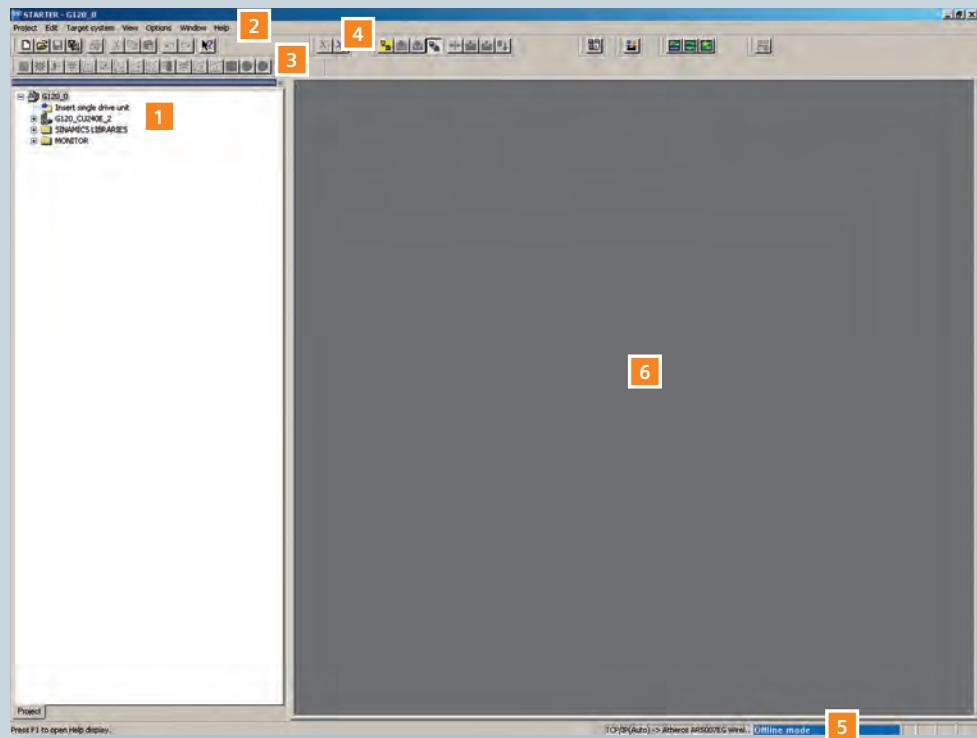
- 8 The identified converter is displayed
- 9 Add the converter to your project with "Insert drive units"
- 10 Close the project wizard with "Complete"

The converter is now integrated into the project tree and the parameters can be set up using the STARTER software.



STARTER user interface

- 1 Project tree
- 2 Program menu
- 3 Toolbar with special features
- 4 Icon "Connect to selected target devices"
- 5 Connection mode
- 6 Work area



Loading converter data

Before you can load the current converter's data into your project, an online connection between the PC and the converter has to be established.

- 1 Click the icon "Connect to selected target devices"
- 2 Set the access point to "DEVICE" and place a checkmark next to converter name
- 3 Click "Load HW configuration to PG"



Now the converter data is loaded into the project and an online connection between PC and converter is established.

- 4 The blue highlighted "Offline mode" changes to the yellow highlighted "Online mode"
- 5 The workbench area opens

Workbench area

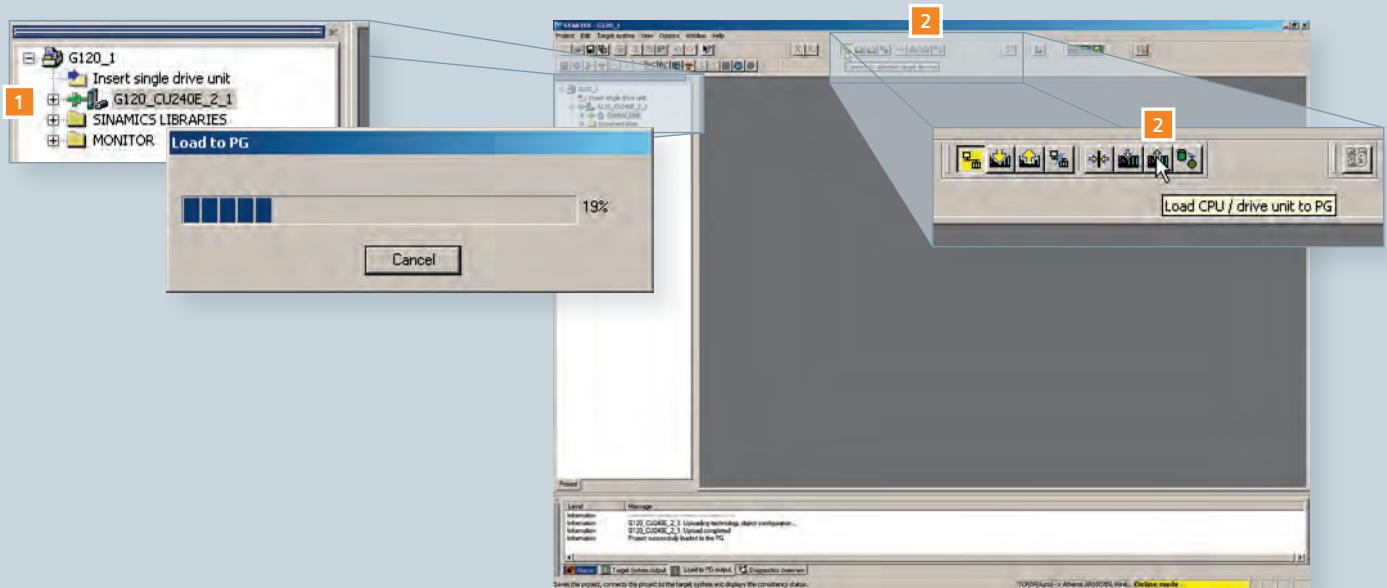
The area provides additional information such as alarms, the target system output and the diagnostics overview. It also stores additional operating features.



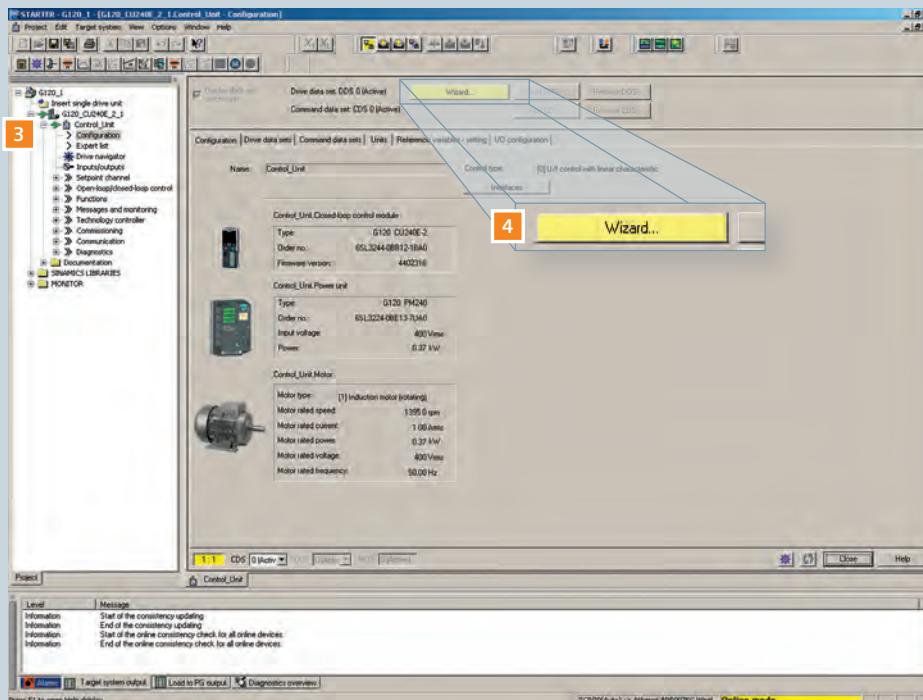
3.2 Parameterization

You can now begin to parameterize your converter.

- 1 Double-click on the converter icon in the project tree
- 2 Click on "Load CPU / drive unit to PG"



- 3 Double-click "Configuration"
- 4 Click "Wizard ..." in the work area and let the wizard guide you



We recommend parameterizing our example using the online mode.

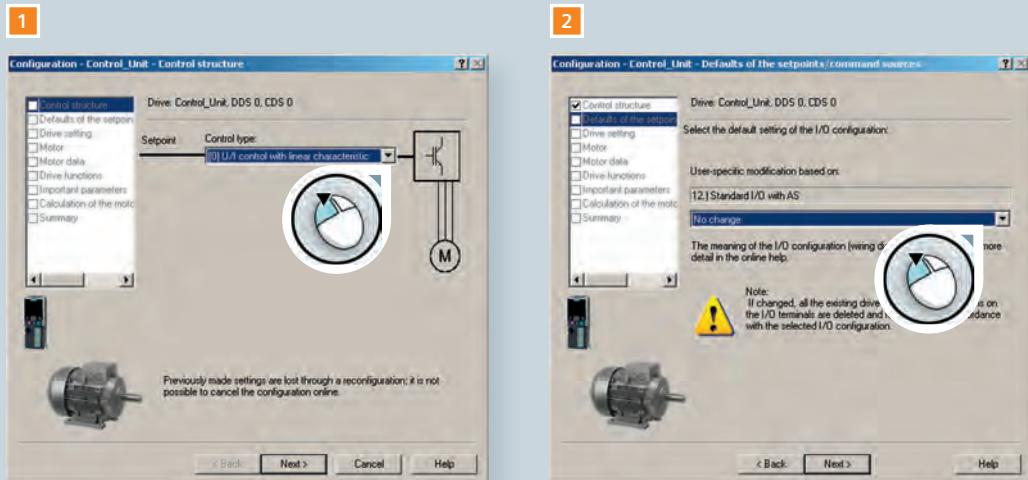
NOTE

Configuration wizard

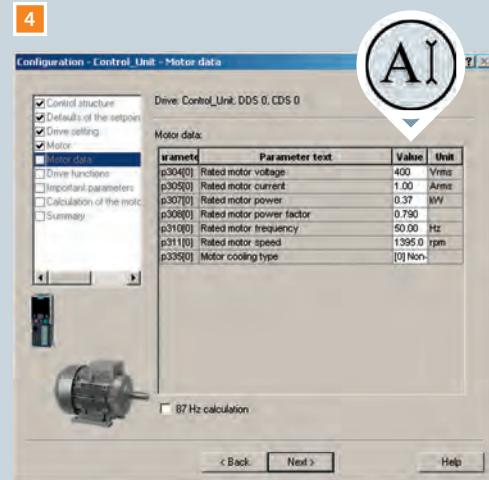
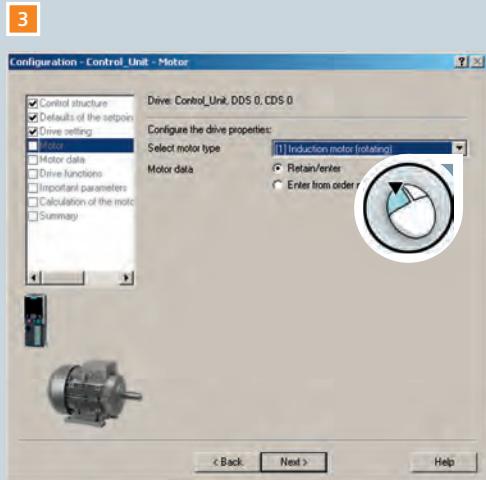
The configuration wizard guides you step by step through the following parameters:

- Control structure
- Defaults of the setpoint source and the command source
- Drive setting
- Motor
- Motor data
- Drive functions
- Important parameters
- Calculation of the motor data
- Summary

By clicking "Next" you get to the next configuration step.



- 1 Start by setting the control structure
- 2 Define the command and setpoint source
- 3 Select the motor type
- 4 Input motor data corresponding to the rating plate



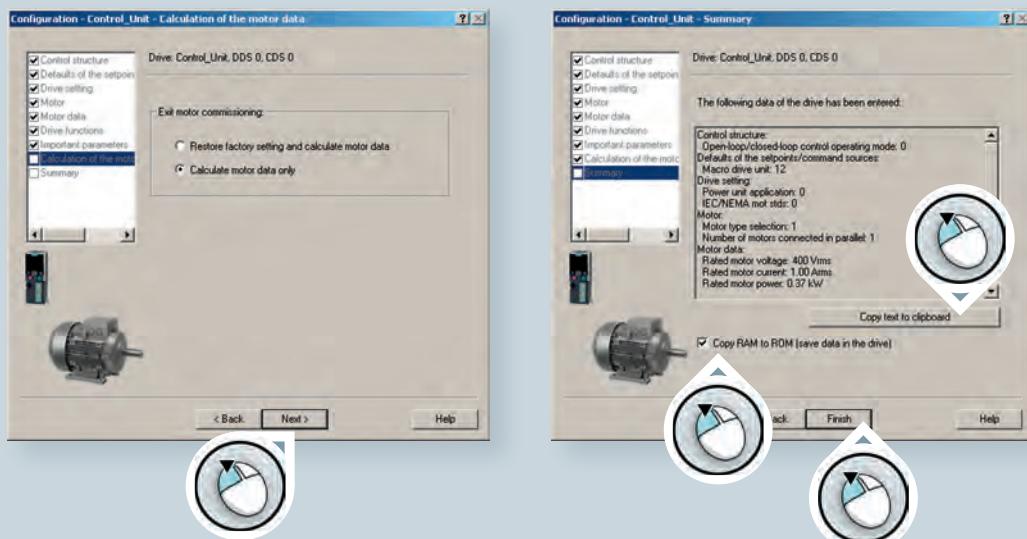
For non-Siemens motors, please use the motor rating plate to input the motor data.

NOTE

- 5 Select "Identify motor data at standstill" for motor data identification
- 6 Enter maximum current
- 7 Enter minimum and maximum speed
- 8 Enter ramp-up, ramp-down time and OFF3 ramp-down time emergency shut-off



After clicking "Next", the calculating of the motor data starts. This concludes the parameterization with the configuration wizard. You will now receive a summary of all parameter values input. The summary can be inserted into a text file by pressing the "Copy text to clipboard" button. Finally select "Copy RAM to ROM" to store the parameterization in the converters ROM memory and close the window by clicking "Finish".



Safety Integrated

If your converter is used in a safety related environment, we strongly recommend performing Safety Integrated engineering using the STARTER. STARTER guides you clearly and easily through the process. Thus, the risk of wrong parameterization is reduced to a minimum.

All control units CU240E-2 come with the Safety Integrated function STO (Safe Torque Off). STO can be used when the motor can decelerate to a standstill within a short period of time. Activating the STO function, immediately ensures that the motor cannot supply any further torque-generating energy.

Advantages for the user:

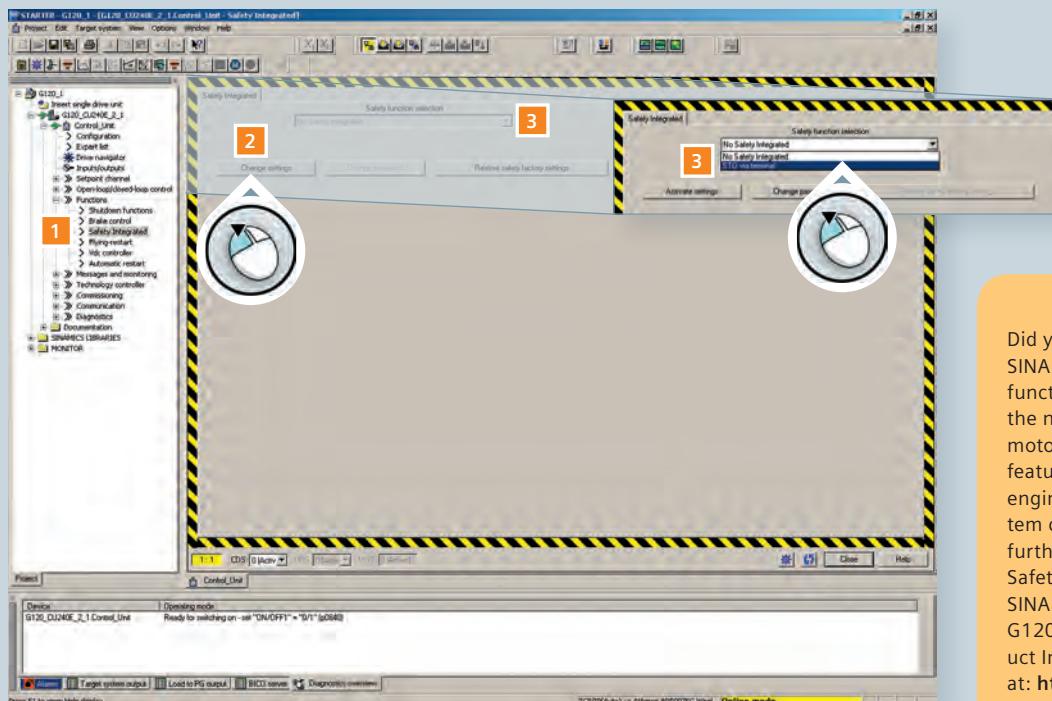
- No wearing parts thanks to electronic shutdown
- Converter remains connected to the supply, it always supports full diagnostics capability
- Password protected, no manipulation of the function possible



The CU240E-2_F and CU240E-2_DP-F Control Units have several Safety functions integrated. In this case, no encoder is needed. Detailed information about SINAMICS Safety Integrated are available at: www.siemens.com/safety-integrated

Activating Safety Integrated

- 1 Browse to "Safety Integrated" in the project tree
- 2 Select "Change settings"
- 3 Choose "STO via terminal" from the drop-down menu



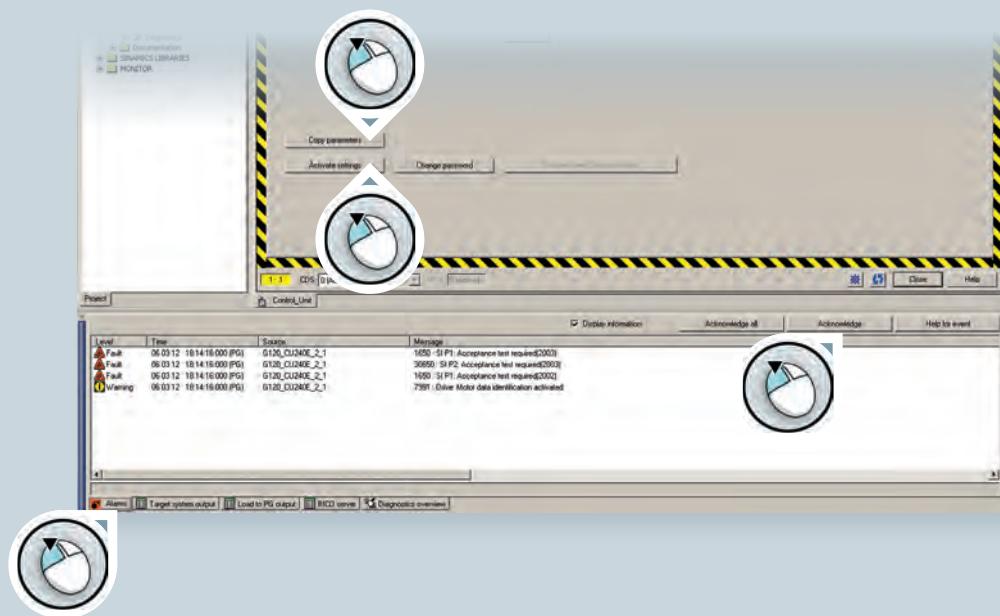
Did you know that extended SINAMICS Safety Integrated functions can be used without the need of an encoder at the motor? This worldwide unique feature saves installation and engineering time, reduces system costs and saves space. For further instructions consult the Safety functional manual SINAMICS G120 and SINAMICS G120C using the Siemens Product Information System (Prodis) at: <http://support.automation.siemens.com/WW/view/en/50736819>

NOTE

- 4 If your converter is connected to a controller, set the output signal to "STO active" in the corresponding drop-down menu
- 5 Click on "extended settings" for further adjustments
- 6 Follow the STARTER instructions

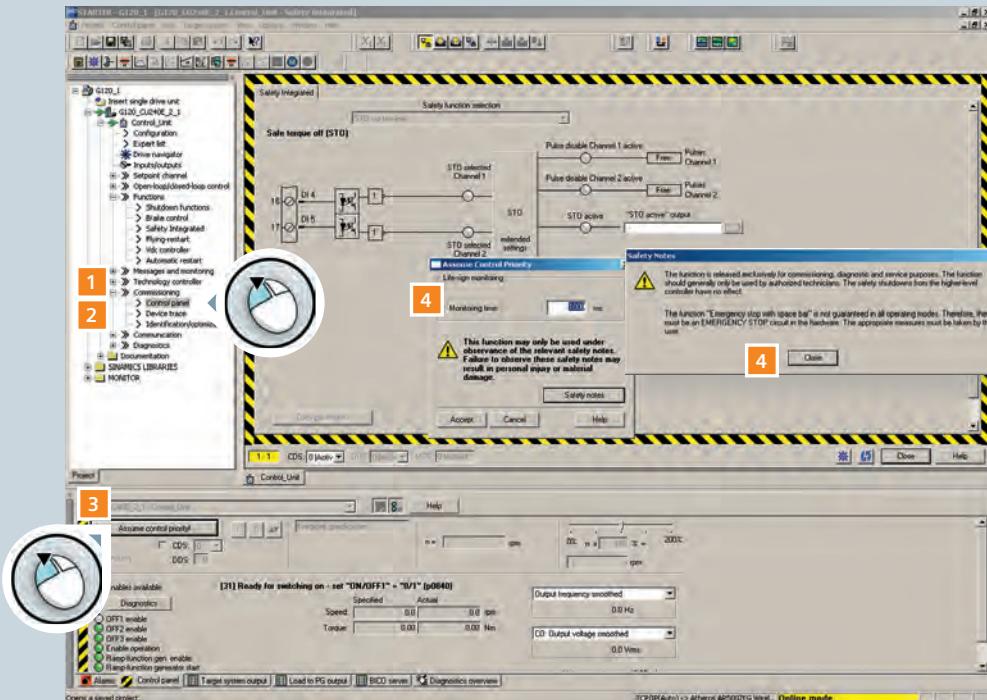


Now your first Safety channel is set. For the second channel just copy the parameters. Clicking "Activate settings" concludes the safety engineering. In the workbench area click on "Alarms" and press the "Acknowledge" button to activate the actually safety functions.



Start motor data identification

- 1 Open the "Commissioning" entry in the project tree
- 2 Double-click "Control panel" in the project tree
- 3 Click on "Assume control priority!" in the workbench area
- 4 A setup window for command transfer opens, accept the displayed values and safety instructions



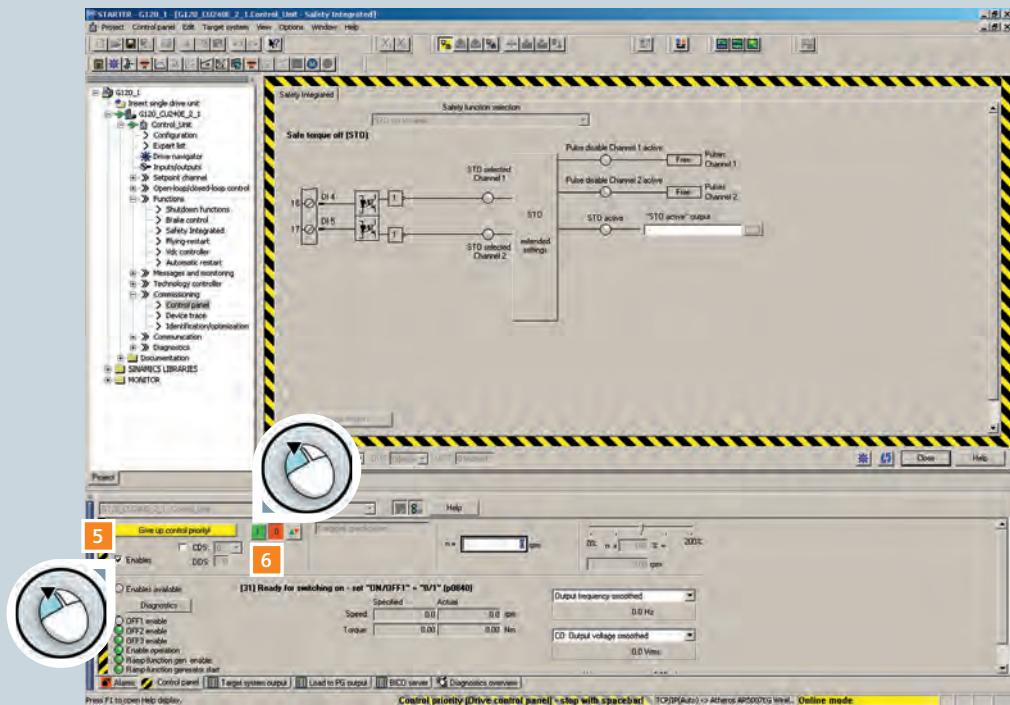
The pending motor data identification is indicated by the message "A7991" in the alarm tab. The message tells you that motor data identification will be performed after switching the motor on.

NOTE

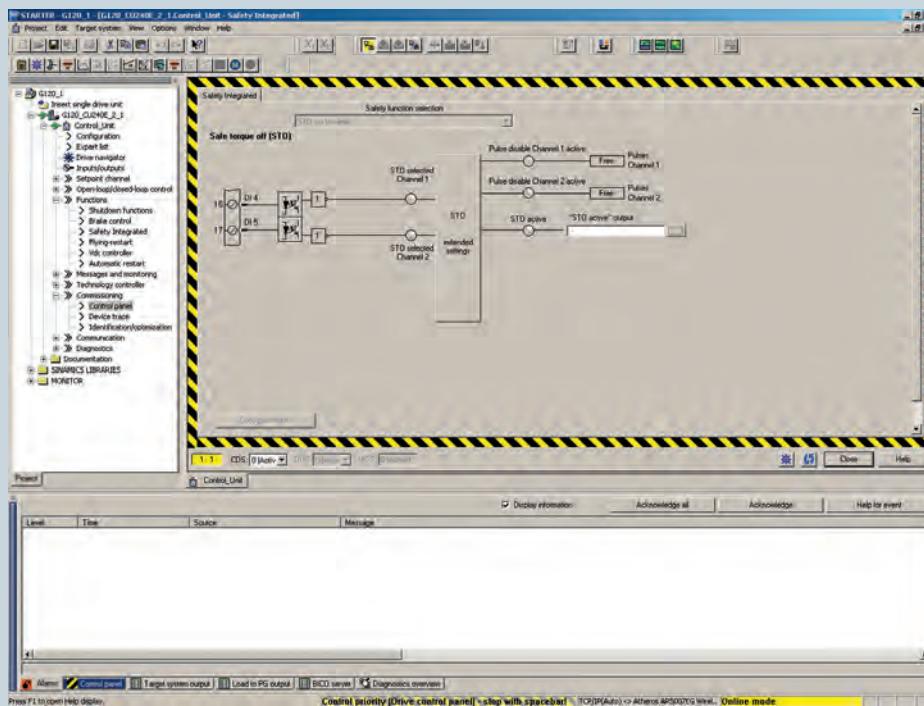
5 Place a checkmark next to “Enables” in the workbench area

Now the STARTER software has control authority for the attached motor.

6 Click the green button to start the motor



Motor data identification is processed. Parameter setup has been successfully completed when Alarm 7991 has disappeared.

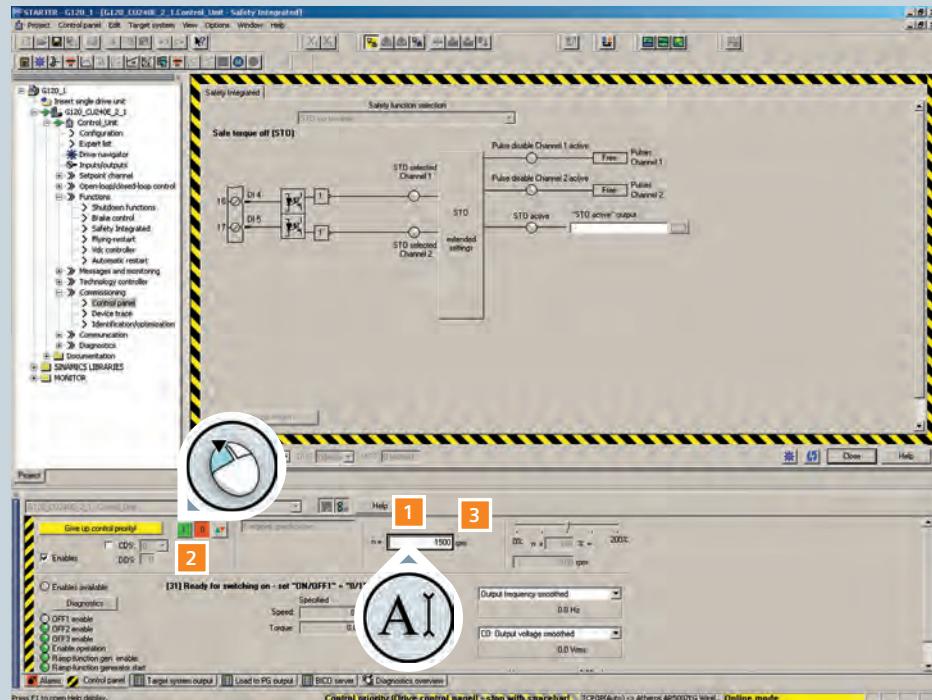


3.3 Application cases

Before returning control authority from the STARTER software to the terminal, you should try controlling the motor from the PC.

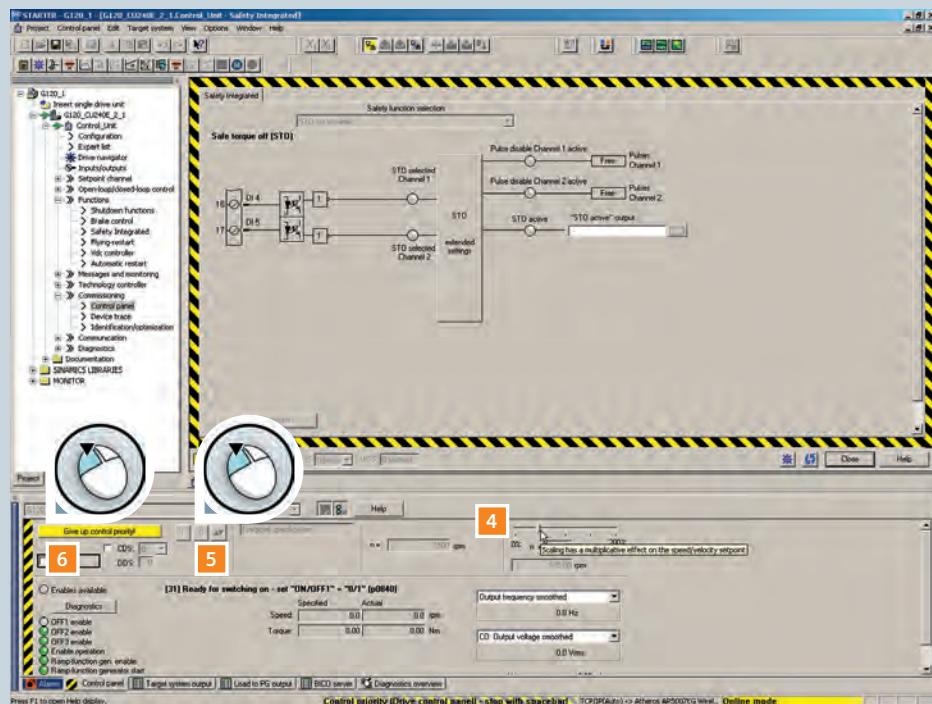
Setting setpoint specifications

- 1 Input 1.500 rpm in the “setpoint specification” box
- 2 Click the green button to start the motor
- 3 See how the motor runs with 1.500 rpm



- 4 Adjust the speed with the slider
- 5 Click the red button to stop the motor
- 6 Conclude the process by clicking "Give up control priority!"

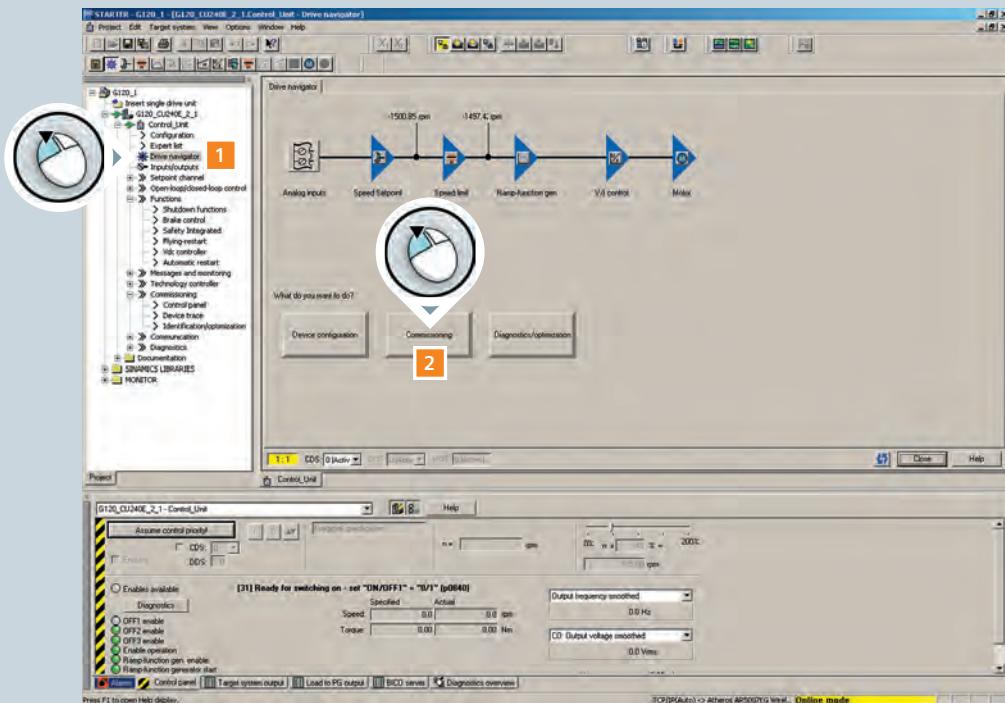
All functions from the displayed control area in the STARTER will be deactivated. The control authority has been returned to the terminal.



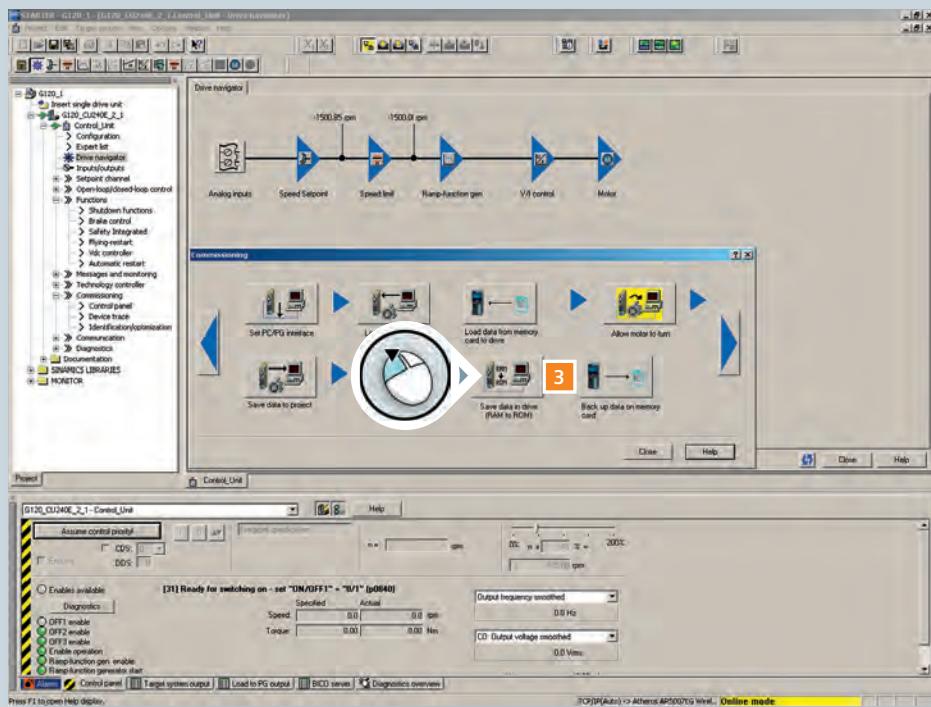
Saving data

A power outage may cause the loss of the parameter settings. As a result, STARTER offers various possibilities for protecting your parameter settings.

- 1 Double-click the “Drive navigator” in the project tree
- 2 Select “Commissioning” in the work area



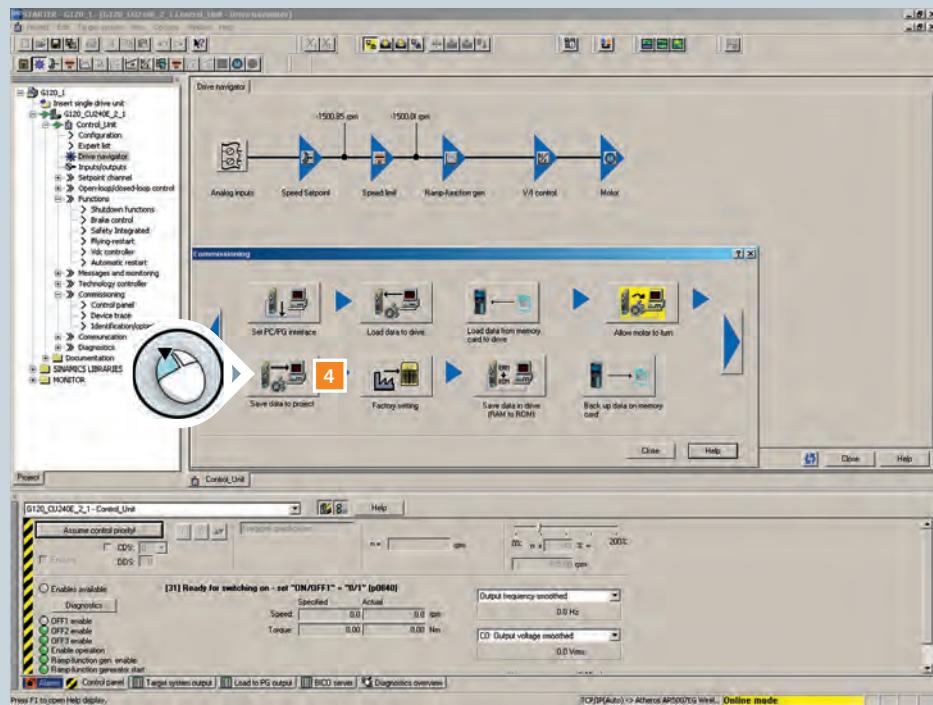
3 Select "Save data in drive (RAM to ROM)" to store the parameter settings in the converter's EEPROM memory



Because you have worked in online mode, no data whatsoever have been stored in your project.

- 4 Click "Save data to project" to save the parameter setting in your project

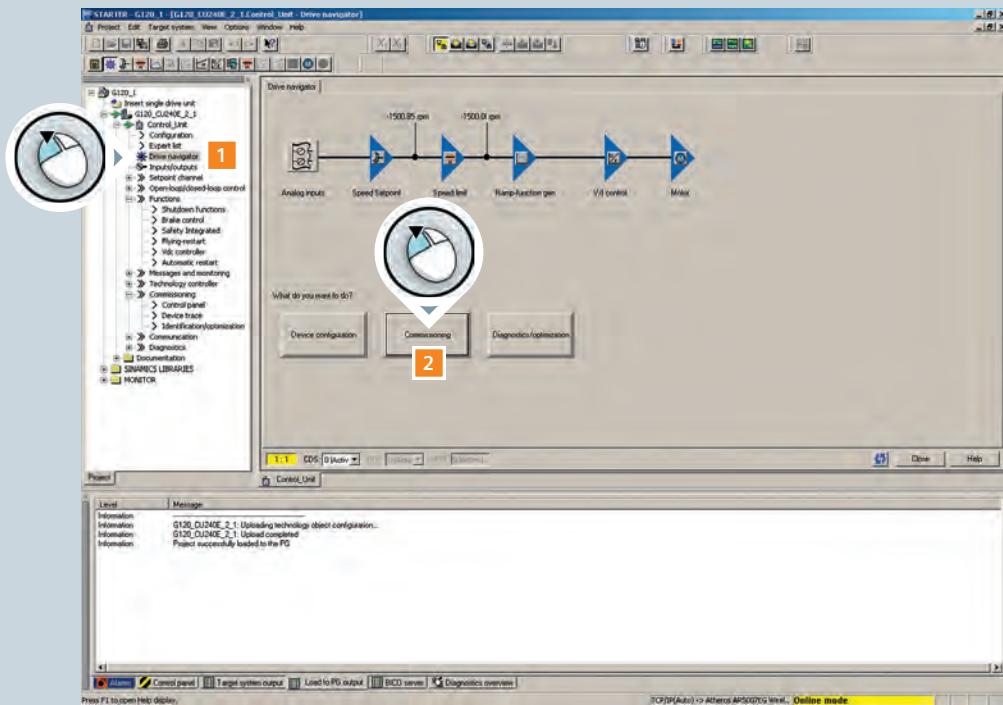
Now you could disconnect the online connection to the converter by clicking the "Disconnect from target system" icon. In our example, please continue to remain online to restore the converter to its factory settings.



Restoring factory settings

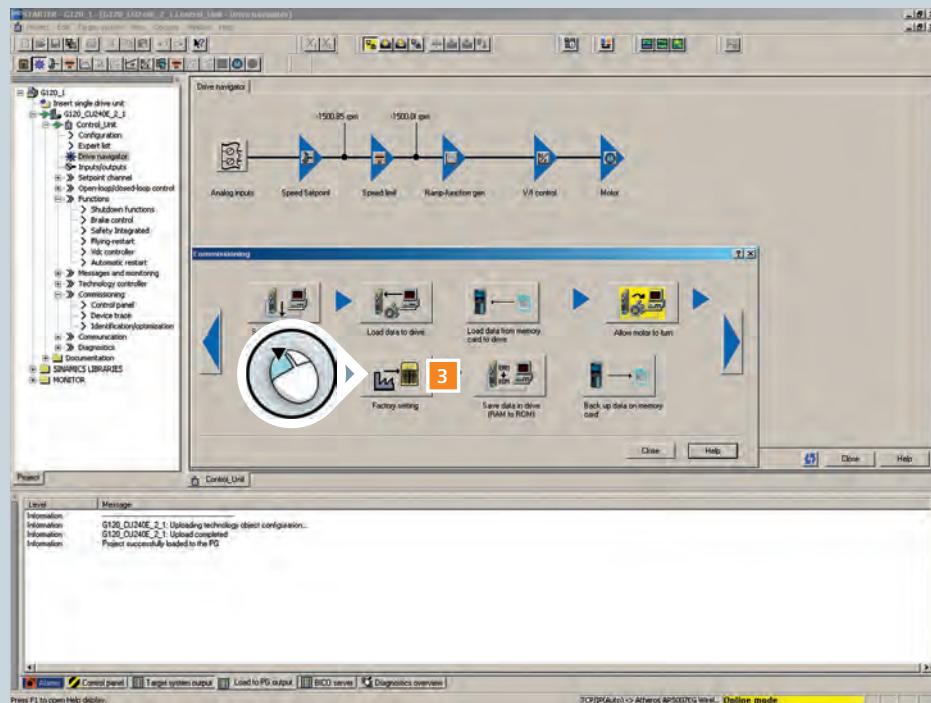
Resetting your converter to factory settings might be helpful if you have experienced any problems during parameterization.

- 1 Double-click the “Drive navigator”
- 2 Select “Commissioning”

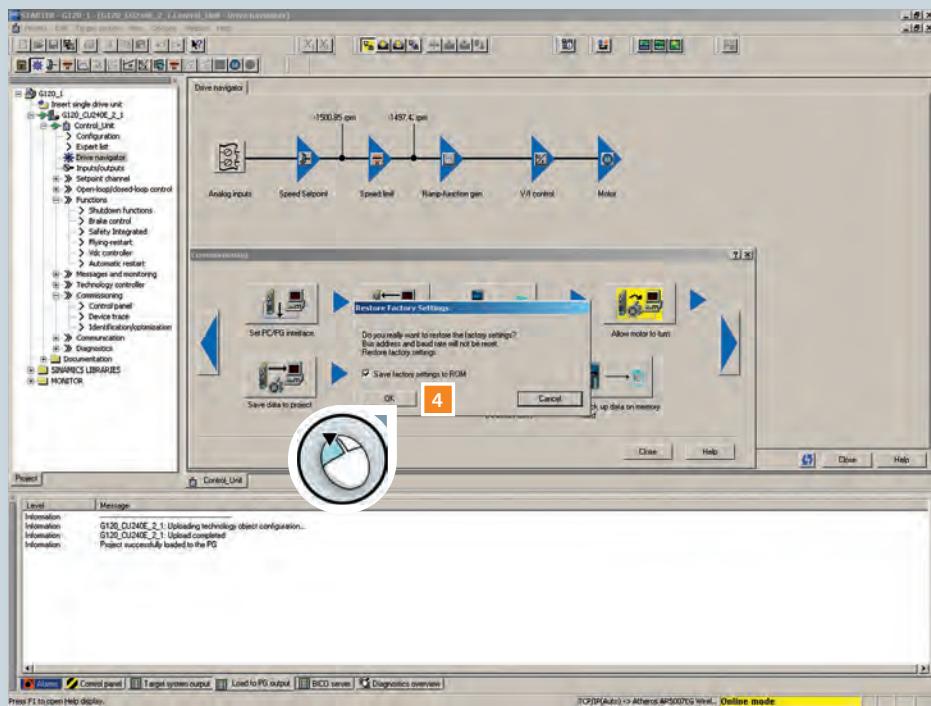


3 Click "Factory settings"

The security query that is now displayed lets you know that all settings you have made will be reset. Using the checkbox query, you will have the opportunity to save your settings to the converter's ROM memory beforehand.

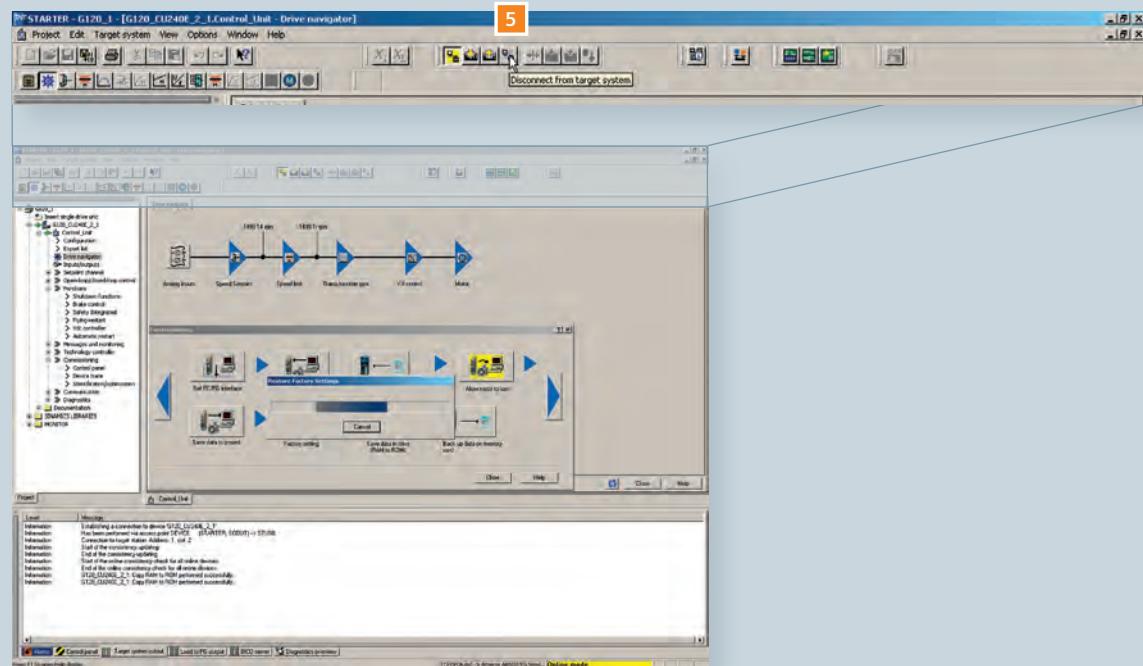


4 Click "OK" to reset all converter settings to the factory setting



5 After reset click "Disconnect from target system"

You now know how to use STARTER to quickly and clearly insert your converter into a project, set up its parameters, and put it into operation. Please make sure that you always remember to save the parameter data to the converter and in the software before exiting a project.



Congratulations!

You have mastered the SINAMICS G120 Training Booklet. Thank you for your time and efforts. We hope that this tutorial has addressed all the questions you had and was useful to you. More detailed information can be found online.



Download overview

Overview of the various control unit versions

<http://www.siemens.com/sinamics-g120/printmaterial>
SINAMICS G120 brochure

Additional information on parameters

<http://support.automation.siemens.com/WW/view/en/49946755>
"Parameter Manual: Control Units – CU240B/E-2"

Detailed information about SINAMICS G120

<http://support.automation.siemens.com/WW/view/en/50815575>
"Operating Instructions: SINAMICS G120 Inverter with CU240B-2 and CU240E-Control Units"

Safety Integrated Function Manual

<http://support.automation.siemens.com/WW/view/en/50736819>

STARTER software

<http://support.automation.siemens.com/WW/view/en/26233208>

Siemens AG
Industry Sector
Drive Technologies
Motion Control

Subject to change
Order No.: 6FC5095-0AA85-0BA0
Dispo: 21200
04/2012 HL 11076147 EN

Printed in Germany

© Siemens AG 2012